

Machine Learning Course 2024 Spring: Homework 3

April 28, 2024

1 Problem 1

Let

$$\mathbf{W}_1 = \begin{bmatrix} w_{1,11} & w_{1,12} & \cdots & w_{1,1n} \\ w_{1,21} & w_{1,22} & \cdots & w_{1,2n} \\ \vdots & \vdots & \ddots & \vdots \\ w_{1,d1} & w_{1,d2} & \cdots & w_{1,dn} \end{bmatrix} \in \mathbb{R}^{d \times n}, \quad \mathbf{W}_2 = \begin{bmatrix} w_{2,11} & w_{2,12} & \cdots & w_{2,1q} \\ w_{2,21} & w_{2,22} & \cdots & w_{2,2q} \\ \vdots & \vdots & \ddots & \vdots \\ w_{2,n1} & w_{2,n2} & \cdots & w_{2,nq} \end{bmatrix} \in \mathbb{R}^{n \times q},$$

$$\mathbf{b}_1 = \begin{bmatrix} b_{1,1} \\ b_{1,2} \\ \vdots \\ b_{1,n} \end{bmatrix} \in \mathbb{R}^n, \quad \mathbf{b}_2 = \begin{bmatrix} b_{2,1} \\ b_{2,2} \\ \vdots \\ b_{2,q} \end{bmatrix} \in \mathbb{R}^q.$$

Then, we have

$$\mathbf{h} = \begin{bmatrix} h_1 \\ h_2 \\ \vdots \\ h_n \end{bmatrix} = \mathbf{W}_1^\top \mathbf{x} + \mathbf{b}_1 = \begin{bmatrix} \sum_{m=1}^d w_{1,m1} \cdot x_m + b_{1,1} \\ \sum_{m=1}^d w_{1,m2} \cdot x_m + b_{1,2} \\ \vdots \\ \sum_{m=1}^d w_{1,mn} \cdot x_m + b_{1,n} \end{bmatrix} \in \mathbb{R}^q,$$

$$\mathbf{z} = \begin{bmatrix} z_1 \\ z_2 \\ \vdots \\ z_q \end{bmatrix} = \mathbf{W}_2^\top \mathbf{a} + \mathbf{b}_2 = \begin{bmatrix} \sum_{l=1}^n w_{2,l1} \cdot a_l + b_{2,1} \\ \sum_{l=1}^n w_{2,l2} \cdot a_l + b_{2,2} \\ \vdots \\ \sum_{l=1}^n w_{2,lq} \cdot a_l + b_{2,q} \end{bmatrix} \in \mathbb{R}^q.$$

Solution:

□

The loss function is

$$\text{Loss} = - \sum_{i=1}^q y_i^s \ln(\hat{y}_i) = - \sum_{i=1}^q \left((1 - \epsilon)y_i + \frac{\epsilon}{q} \right) \ln(\hat{y}_i). \quad (1)$$

The derivative of the loss function w.r.t \hat{y}_i ($1 \leq i \leq q$) is

$$\begin{aligned} \frac{\partial \text{Loss}}{\partial \hat{y}_i} &= - \sum_{i=1}^q \frac{\partial \left((1 - \epsilon)y_i + \frac{\epsilon}{q} \right) \ln(\hat{y}_i)}{\partial \hat{y}_i} \\ &= -(1 - \epsilon) \sum_{i=1}^q \frac{y_i}{\hat{y}_i} - \frac{\epsilon}{q} \sum_{i=1}^q \frac{1}{\hat{y}_i}. \end{aligned} \quad (2)$$

The derivative of the soft-max function w.r.t z_j ($1 \leq j \leq q$) is

$$\frac{\partial \hat{y}_i}{\partial z_j} = \frac{\frac{\partial \exp(z_i)}{\partial z_j} \sum_{k=1}^q \exp(z_k) - \exp(z_i) \frac{\partial \sum_{k=1}^q \exp(z_k)}{\partial z_j}}{\left(\sum_{k=1}^q \exp(z_k) \right)^2}. \quad (3)$$

When $i = j$, we have

$$\begin{aligned} \frac{\partial \hat{y}_i}{\partial z_j} &= \frac{\exp(z_i) \sum_{k=1}^q \exp(z_k) - \exp(z_i) \exp(z_j)}{\left(\sum_{k=1}^q \exp(z_k) \right)^2} \\ &= \hat{y}_i(1 - \hat{y}_j). \end{aligned} \quad (4)$$

When $i \neq j$, we have

$$\begin{aligned} \frac{\partial \hat{y}_i}{\partial z_j} &= \frac{0 \sum_{k=1}^q \exp(z_k) - \exp(z_i) \exp(z_j)}{\left(\sum_{k=1}^q \exp(z_k) \right)^2} \\ &= -\hat{y}_i \hat{y}_j. \end{aligned} \quad (5)$$

So, the derivative of the soft-max function w.r.t z_j is

$$\frac{\partial \hat{y}_i}{\partial z_j} = \begin{cases} \hat{y}_i(1 - \hat{y}_j), & \text{if } i = j, \\ -\hat{y}_i \hat{y}_j, & \text{if } i \neq j. \end{cases} \quad (6)$$

According to Eq.(2) and Eq.(6), the derivative of the loss function w.r.t z_j is

$$\begin{aligned}
\frac{\partial \text{Loss}}{\partial z_j} &= \frac{\partial \text{Loss}}{\partial \hat{y}_i} \frac{\partial \hat{y}_i}{\partial z_j} \\
&= -(1-\epsilon) \sum_{i=1}^q \frac{y_i}{\hat{y}_i} \frac{\partial \hat{y}_i}{\partial z_j} - \frac{\epsilon}{q} \sum_{i=1}^q \frac{1}{\hat{y}_i} \frac{\partial \hat{y}_i}{\partial z_j} \\
&= (1-\epsilon) \left(-\frac{y_j}{\hat{y}_j} \hat{y}_j (1-\hat{y}_j) + \sum_{i=1, i \neq j}^q \frac{y_i}{\hat{y}_i} \hat{y}_i \hat{y}_j \right) + \frac{\epsilon}{q} \left(-\frac{1}{\hat{y}_j} \hat{y}_j (1-\hat{y}_j) + \sum_{i=1, i \neq j}^q \frac{1}{\hat{y}_i} \hat{y}_i \hat{y}_j \right) \\
&= (1-\epsilon) (-y_j + y_j \hat{y}_j + \sum_{i=1, i \neq j}^q y_i \hat{y}_j) + \frac{\epsilon}{q} (-1 + \hat{y}_j + \sum_{i=1, i \neq j}^q \hat{y}_j) \\
&= (1-\epsilon) (-y_j + \sum_{i=1}^q y_i \hat{y}_j) + \frac{\epsilon}{q} (-1 + \sum_{i=1}^q \hat{y}_j) \\
&= (1-\epsilon) (\hat{y}_j - y_j) + \frac{\epsilon}{q} (q \hat{y}_j - 1) \\
&= \hat{y}_j - (1-\epsilon) y_j - \frac{\epsilon}{q}.
\end{aligned} \tag{7}$$

The derivative of z_j w.r.t $w_{2,kj}$ ($1 \leq k \leq n, 1 \leq j \leq q$) is

$$\frac{\partial z_j}{\partial w_{2,kj}} = \frac{\partial (\sum_{l=1}^n w_{2,lj} \cdot a_l + b_{2,j})}{\partial w_{2,kj}} = a_k. \tag{8}$$

According to Eq.(7) and Eq.(8), we have

$$\frac{\partial \text{Loss}}{\partial w_{2,kj}} = \frac{\partial \text{Loss}}{\partial z_j} \frac{\partial z_j}{\partial w_{2,kj}} = \left(\hat{y}_j - (1-\epsilon) y_j - \frac{\epsilon}{q} \right) \cdot a_k. \tag{9}$$

Thus,

$$\frac{\partial \text{Loss}}{\partial \mathbf{W}_2} = \begin{bmatrix} \left(\hat{y}_1 - (1-\epsilon) y_1 - \frac{\epsilon}{q} \right) \cdot a_1 & \left(\hat{y}_2 - (1-\epsilon) y_2 - \frac{\epsilon}{q} \right) \cdot a_1 & \cdots & \left(\hat{y}_n - (1-\epsilon) y_n - \frac{\epsilon}{q} \right) \cdot a_1 \\ \left(\hat{y}_1 - (1-\epsilon) y_1 - \frac{\epsilon}{q} \right) \cdot a_2 & \left(\hat{y}_2 - (1-\epsilon) y_2 - \frac{\epsilon}{q} \right) \cdot a_2 & \cdots & \left(\hat{y}_n - (1-\epsilon) y_n - \frac{\epsilon}{q} \right) \cdot a_2 \\ \vdots & \vdots & \ddots & \vdots \\ \left(\hat{y}_1 - (1-\epsilon) y_1 - \frac{\epsilon}{q} \right) \cdot a_q & \left(\hat{y}_2 - (1-\epsilon) y_2 - \frac{\epsilon}{q} \right) \cdot a_q & \cdots & \left(\hat{y}_n - (1-\epsilon) y_n - \frac{\epsilon}{q} \right) \cdot a_q \end{bmatrix}. \tag{10}$$

The derivative of z_j w.r.t $b_{2,j}$ ($1 \leq j \leq q$) is

$$\frac{\partial z_j}{\partial b_{2,j}} = \frac{\partial (\sum_{l=1}^n w_{2,lj} \cdot a_l + b_{2,j})}{\partial b_{2,j}} = 1. \tag{11}$$

According to Eq.(7) and Eq.(11), we have

$$\frac{\partial \text{Loss}}{\partial b_{2,j}} = \frac{\partial \text{Loss}}{\partial z_j} \frac{\partial z_j}{\partial b_{2,j}} = \hat{y}_j - (1-\epsilon) y_j - \frac{\epsilon}{q}. \tag{12}$$

Thus,

$$\frac{\partial \text{Loss}}{\partial \mathbf{b}_2} = \begin{bmatrix} \hat{y}_1 - (1-\epsilon) y_1 - \frac{\epsilon}{q} \\ \hat{y}_2 - (1-\epsilon) y_2 - \frac{\epsilon}{q} \\ \vdots \\ \hat{y}_q - (1-\epsilon) y_q - \frac{\epsilon}{q} \end{bmatrix}. \tag{13}$$

The derivative of z_j w.r.t a_p ($1 \leq p \leq n$) is

$$\frac{\partial z_j}{\partial a_p} = \frac{\partial(\sum_{l=1}^n w_{2,lj} \cdot a_l + b_{2,j})}{\partial a_p} = w_{2,pj}. \quad (14)$$

The derivative of the ReLU activation function w.r.t h_p ($1 \leq p \leq n$) is

$$f(h_i) = \frac{\partial a_p}{\partial h_p} = \frac{\partial \text{ReLU}(h_p)}{\partial h_p} = \begin{cases} 0, & \text{if } h_i < 0, \\ 1, & \text{otherwise.} \end{cases} \quad (15)$$

The derivative of h_p w.r.t $w_{1,rp}$ ($1 \leq r \leq d, 1 \leq p \leq n$) is

$$\frac{\partial h_p}{\partial w_{1,rp}} = \frac{\partial(\sum_{m=1}^d w_{1,mp} \cdot x_m + b_{2,p})}{\partial w_{1,rp}} = x_r. \quad (16)$$

According to Eq.(7), Eq.(14), Eq.(15) and Eq.(16) we have

$$\frac{\partial \text{Loss}}{\partial w_{1,rp}} = \sum_{s=1}^q \left(\frac{\partial \text{Loss}}{\partial z_s} \frac{\partial z_s}{\partial a_p} \right) \frac{\partial a_p}{\partial h_p} \frac{\partial h_p}{\partial w_{1,rp}} = \left(\sum_{s=1}^q g_s \cdot w_{2,ps} \right) \cdot f(h_p) \cdot x_r. \quad (17)$$

Thus,

$$\frac{\partial \text{Loss}}{\partial \mathbf{W}_1} = \begin{bmatrix} (\sum_{s=1}^q g_s w_{2,1s}) \cdot f(h_1) \cdot x_1 & (\sum_{s=1}^q g_s w_{2,2s}) \cdot f(h_2) \cdot x_1 & \cdots & (\sum_{s=1}^q g_s w_{2,ns}) \cdot f(h_n) \cdot x_1 \\ (\sum_{s=1}^q g_s w_{2,1s}) \cdot f(h_1) \cdot x_2 & (\sum_{s=1}^q g_s w_{2,2s}) \cdot f(h_2) \cdot x_2 & \cdots & (\sum_{s=1}^q g_s w_{2,ns}) \cdot f(h_n) \cdot x_2 \\ \vdots & \vdots & \ddots & \vdots \\ (\sum_{s=1}^q g_s w_{2,1s}) \cdot f(h_1) \cdot x_d & (\sum_{s=1}^q g_s w_{2,2s}) \cdot f(h_2) \cdot x_d & \cdots & (\sum_{s=1}^q g_s w_{2,ns}) \cdot f(h_n) \cdot x_d \end{bmatrix}, \quad (18)$$

where $g_s = \left(\hat{y}_s - (1 - \epsilon)y_s - \frac{\epsilon}{q} \right)$.

The derivative of h_p w.r.t $b_{1,p}$ ($1 \leq p \leq n$) is

$$\frac{\partial h_p}{\partial b_{1,p}} = \frac{\partial(\sum_{m=1}^d w_{1,mp} \cdot x_m + b_{1,p})}{\partial b_{1,p}} = 1. \quad (19)$$

According to Eq.(7), Eq.(14), Eq.(15) and Eq.(19) we have

$$\frac{\partial \text{Loss}}{\partial b_{1,p}} = \sum_{s=1}^q \left(\frac{\partial \text{Loss}}{\partial z_s} \frac{\partial z_s}{\partial a_p} \right) \frac{\partial a_p}{\partial h_p} \frac{\partial h_p}{\partial b_{1,p}} = \left(\sum_{s=1}^q g_s \cdot w_{2,ps} \right) \cdot f(h_p) \cdot x_r. \quad (20)$$

Thus,

$$\frac{\partial \text{Loss}}{\partial \mathbf{b}_1} = \begin{bmatrix} (\sum_{s=1}^q g_s \cdot w_{2,1s}) \cdot f(h_1) \\ (\sum_{s=1}^q g_s \cdot w_{2,2s}) \cdot f(h_2) \\ \vdots \\ (\sum_{s=1}^q g_s \cdot w_{2,ns}) \cdot f(h_n) \end{bmatrix}. \quad (21)$$

2 Problem 2

First, we consider the feed-forward process:

$$\mathbf{h} = \mathbf{W}_1^\top \mathbf{x} + \mathbf{b}_1 = \begin{bmatrix} -13 \\ 2 \\ -5 \end{bmatrix}, \mathbf{a} = \text{ReLU}(\mathbf{h}) = \begin{bmatrix} 0 \\ 2 \\ 0 \end{bmatrix},$$

$$\mathbf{z} = \mathbf{W}_2^\top \mathbf{a} + \mathbf{b}_2 = \begin{bmatrix} 0 \\ -3 \\ 1 \end{bmatrix}, \hat{\mathbf{y}} = \text{Softmax}(\mathbf{z}) = \begin{bmatrix} 0.2654 \\ 0.0132 \\ 0.7214 \end{bmatrix},$$

$$\text{Loss} = - \sum_{i=1}^q y_i^s \ln(\hat{y}_i) = 1.5266.$$

Then, we compute the back-propagation using Eq.(10), Eq.(13), Eq.(18) and Eq.(21):

$$\frac{\partial \text{Loss}}{\partial \mathbf{W}_2} = \begin{bmatrix} a_1 \cdot (\hat{y}_1 - 0.8) & a_1 \cdot (\hat{y}_2 - 0.1) & a_1 \cdot (\hat{y}_3 - 0.1) \\ a_2 \cdot (\hat{y}_1 - 0.8) & a_2 \cdot (\hat{y}_2 - 0.1) & a_2 \cdot (\hat{y}_3 - 0.1) \\ a_3 \cdot (\hat{y}_1 - 0.8) & a_3 \cdot (\hat{y}_2 - 0.1) & a_3 \cdot (\hat{y}_3 - 0.1) \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 \\ -1.0692 & -0.1736 & 1.2428 \\ 0 & 0 & 0 \end{bmatrix},$$

$$\frac{\partial \text{Loss}}{\partial \mathbf{b}_2} = \begin{bmatrix} \hat{y}_1 - 0.8 \\ \hat{y}_2 - 0.1 \\ \hat{y}_3 - 0.1 \end{bmatrix} = \begin{bmatrix} -0.5346 \\ -0.0868 \\ 0.6214 \end{bmatrix},$$

$$\begin{aligned} \frac{\partial \text{Loss}}{\partial \mathbf{W}_1} &= \begin{bmatrix} 0 & 0 & 0 \\ 0 & (\sum_{s=1}^q g_s w_{2,2s}) \cdot x_2 & 0 \end{bmatrix} \\ &= \begin{bmatrix} 0 & 0 & 0 \\ 0 & [-0.5346 \times (-2) + (-0.0868) \times (-4) + 0.6214 \times (-2)] \cdot 2 & 0 \end{bmatrix} \\ &= \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0.3472 & 0 \end{bmatrix}, \end{aligned}$$

$$\begin{aligned}\frac{\partial \text{Loss}}{\partial \mathbf{b}_1} &= \begin{bmatrix} 0 \\ \sum_{s=1}^q g_s \cdot w_{2,2s} \\ 0 \end{bmatrix} \\ &= \begin{bmatrix} 0 \\ -0.5346 \times (-2) + (-0.0868) \times (-4) + 0.6214 \times (-2) \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0.1736 \\ 0 \end{bmatrix}.\end{aligned}$$

Given the gradients above, we update the parameters as follows:

$$\begin{aligned}\mathbf{W}_2 \leftarrow \mathbf{W}_2 - \eta \cdot \frac{\partial \text{Loss}}{\partial \mathbf{W}_2} &= \begin{bmatrix} 3 & -4 & 1 \\ -2 & -4 & -2 \\ -4 & -2 & 3 \end{bmatrix} - 0.1 \times \begin{bmatrix} 0 & 0 & 0 \\ -1.0692 & -0.1736 & 1.2428 \\ 0 & 0 & 0 \end{bmatrix} \\ &= \begin{bmatrix} 3 & -4 & 1 \\ -1.8931 & -3.9826 & -2.1243 \\ -4 & -2 & 3 \end{bmatrix},\end{aligned}$$

$$\mathbf{b}_2 \leftarrow \mathbf{b}_2 - \eta \cdot \frac{\partial \text{Loss}}{\partial \mathbf{b}_2} = \begin{bmatrix} 4 \\ 5 \\ 5 \end{bmatrix} - 0.1 \times \begin{bmatrix} -0.5346 \\ -0.0868 \\ 0.6214 \end{bmatrix} = \begin{bmatrix} 4.0535 \\ 5.0087 \\ 4.9379 \end{bmatrix},$$

$$\begin{aligned}\mathbf{W}_1 \leftarrow \mathbf{W}_1 - \eta \cdot \frac{\partial \text{Loss}}{\partial \mathbf{W}_1} &= \begin{bmatrix} -5 & 2 & 2 \\ -5 & 2 & -1 \end{bmatrix} - 0.1 \times \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0.3472 & 0 \end{bmatrix} \\ &= \begin{bmatrix} -5 & 2 & 2 \\ -5 & 1.9653 & -1 \end{bmatrix},\end{aligned}$$

$$\mathbf{b}_1 \leftarrow \mathbf{b}_1 - \eta \cdot \frac{\partial \text{Loss}}{\partial \mathbf{b}_1} = \begin{bmatrix} -3 \\ -2 \\ -3 \end{bmatrix} - 0.1 \times \begin{bmatrix} 0 \\ 0.1736 \\ 0 \end{bmatrix} = \begin{bmatrix} -3 \\ -2.0174 \\ -3 \end{bmatrix}.$$